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Detecting shifts in correlation and variability with application to ENSO-Monsoon Rainfall relationships

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With 3 Figures

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15 Summary

16 This paper addresses the retrospective detection of step
17 changes at unknown time points in the correlation structure of
18 two or more climate times series. Both the variance of in-
19 dividual series and the covariance between series are ad-
20 dressed. For a sequence of vector-valued observations with an
21 approximate multivariate normal distribution, the proposed
22 method is a parametric likelihood ratio test of the hypothesis
23 of constant covariance against the hypothesis of at least one
24 shift in covariance. The formulation of the test statistic and
25 its asymptotic distribution are taken from Chen and Gupta
26 (2000). This test is applied to the series comprised of the
27 mean summer NINO3 index and the Indian monsoon rainfall
28 index for the years 1871–2003. The most likely change point
29 year was found to be 1980, with a resulting p -value of
30 0.12. The same test was applied to the series of NINO3 and
31 Northeast Brazil rainfall observations from the years 1856–
32 2001. A shift was detected in 1982 which is significant at
33 the 1% level. Some or all of this shift in the covariance matrix
34 can be attributed to a change in the variance of the Northeast
35 Brazil rainfall. A variation of this methodology designed to
36 increase power under certain multiple change point alterna-
37 tives, specifically when a shift is followed by a reversal, is
38 also presented. Simulations to assess the power of the test
39 under various alternatives are also included, in addition to a
40 review of the literature on alternative methods.

1. Introduction 41

Assessing the stability over time of climate processes and the connections between them is crucial to our understanding of a changing climate. Changes in variability or connections between processes, if robust, can profoundly change our assessment of climate impacts and affect climate predictability. An area of great recent concern is the relationship between the Indian monsoon rainfall (IMR) and the El Niño/Southern Oscillation (ENSO) phenomenon. The existence of a significant negative correlation between time series has been long been observed (Walker and Bliss 1937), but whether the strength of the relationship has decreased in recent decades is a subject of current debate.

Running correlation analysis, in which correlations are computed in overlapping moving windows, has frequently been used in an attempt to document and understand changes in the correlation between two climate indices. In particular, the existence of low-frequency modes of variability is of current interest in many areas of climate research, and running correlations have been used to represent the multi-decadal evolution of the relationship between two processes.

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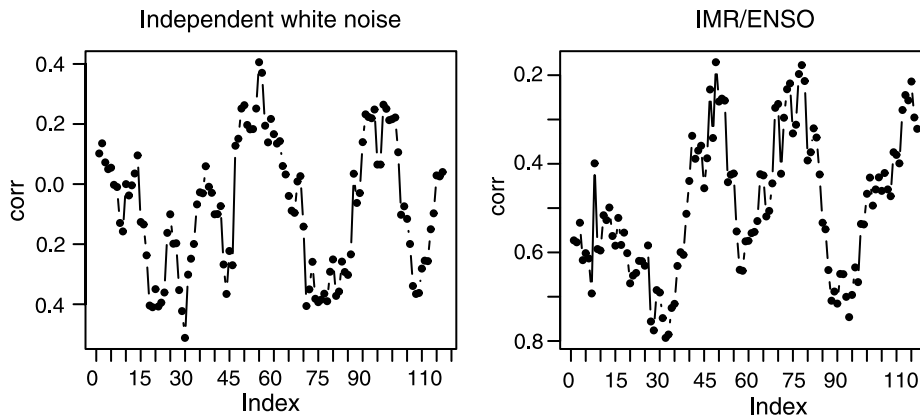


Fig. 1. Comparing the 21-year windowed running correlations of the IMR/ENSO time series with those of two uncorrelated simulated white noise processes illustrates Gershunov et al.'s (2001) observation that apparent periodic fluctuations in running correlations are not reliable indicators of a changing underlying correlation structure, as these fluctuations exist even in stable, uncorrelated processes

1 Among others, Krishnamurthy and Goswami
 2 (2000) have used running correlations to argue
 3 for the existence of low-frequency (15–25 year)
 4 oscillations in the relationship between the IMR
 5 and ENSO. Parthasarathy et al. (1991) used
 6 similar techniques to examine the relationships
 7 between monsoon rainfall and other climate
 8 variables.

9 However, Gershunov et al. (2001) have shown
 10 that there are serious problems in the physical
 11 interpretation of the results of a running-correla-
 12 tion analysis. These problems stem from the fact
 13 that a running correlation analysis applied to any
 14 two processes, even independent processes, pro-
 15 duces what appears to be a low-frequency peri-
 16 odic evolution in the correlation. This however, is
 17 merely an artifact of the method itself and does
 18 not reflect any characteristic of the relationship
 19 between the processes. Sample correlations are
 20 inherently subject to random fluctuations, and
 21 the overlapping nature of the running correla-
 22 tions turns these fluctuations into smooth trends.
 23 Figure 1 (and similar figures in Gershunov et al.
 24 (2001)) compares the results of running correla-
 25 tion analysis of the ENSO/IMR relationship and
 26 of two uncorrelated white noise processes.

27 Gershunov et al. (2001) propose a method of
 28 determining whether observed fluctuations in run-
 29 ning correlations are different from what would
 30 be expected by chance. They suggest comparing
 31 the standard deviation (SD) of an observed series
 32 of running correlations with upper and lower con-
 33 fidence bounds computed from the bootstrapped

SDs of simulated processes with stationary 34
 correlations. 35

In their scheme, the SD of the running correla- 36
 tions of the ENSO/IMR series is compared to 37
 simulations of bivariate Gaussian observations 38
 with a correlation of 0.6 (the correlation of the 39
 entire ENSO/IMR series is about -0.6). They 40
 find that the ENSO/IMR series is actually signifi- 41
 cantly *less* variable than the simulations, with 42
 the observed SD below 5th percentile of the boot- 43
 strapped SDs of the simulations. They suggest 44
 that there is a physical process moderating the 45
 fluctuations of the sliding correlations. 46

While Gershunov et al.'s simulations help to 47
 illuminate the distribution of a running correla- 48
 tion series with constant correlation, the use of 49
 the SDs of the running correlation to character- 50
 ize the evolution of the process is an indirect way to 51
 address the issue of a potentially changing rela- 52
 tionship. The hypotheses being tested using their 53
 proposed method are not clearly related to the 54
 behavior of the processes themselves. Rather, 55
 they refer only to their running correlations, sta- 56
 tistics whose variability does not give clear in- 57
 sight into the underlying correlation structure. 58

Kwon et al. (2005) use running correlation 59
 analysis and empirical orthogonal functions to 60
 examine the connection between ENSO and the 61
 Western North Pacific (WNP) summer monsoon. 62
 They apply the significance test suggested by 63
 Gershunov and find that the variation in the slid- 64
 ing correlations is significant at the 10% confi- 65
 dence level. Based on a comparison of the first 66

1 two leading empirical orthogonal functions (EOF)
2 of WNP summer-mean precipitation (based on
3 station data), they conclude that the relationship
4 in the period from 1994–2003 is weaker than in
5 1979–1993. In the first time period they find that
6 the first mode of variation is one which is highly
7 correlated with ENSO, and the second mode is
8 highly correlated with another precipitation in-
9 dex, WNP Monsoon index (WNPMI). In the lat-
10 ter period, they find the same 2 dominant modes,
11 but the order is reversed. In other words, the
12 ENSO mode is the first dominant mode in the
13 1979–1993 period, and drops to the second dom-
14 inant mode in the 1994–2004 period. The authors
15 conclude from this that the relationship with
16 ENSO has weakened. This is clearly an interest-
17 ing observation, but it is difficult to firmly dis-
18 tinguish from chance variability without knowing
19 the probability of such a reversal happening
20 by chance.

21 Maraun and Kurths (2005) use nonlinear time-
22 series methods to investigate the evolution of the
23 phase coherence between ENSO and IMR series
24 over the 1871–2004 time period. They decom-
25 pose the interannual oscillation dynamics of the
26 two series into amplitude and phase, assessing
27 the relationship between them in terms of phase
28 coherence irrespective of the amplitude. They
29 find periods (1886–1908) and (1964–1980) in
30 which the phases are strongly coupled in com-
31 parison to the rest of the time period. They also
32 develop a simulation scheme by which to judge
33 statistical significance. Empirical probabilities of
34 typical lengths of interannual oscillations are
35 computed from the ENSO and AIR series and
36 used to create 1,000,000 pairs of annually re-
37 solved 150-year time series. Based on the simu-
38 lations, the observed periods of phase coherence
39 are found to be highly significant.

40 Kumar et al. (1999) use resampling methods
41 to estimate the 95% upper confidence bound for
42 21-year sliding correlations and conclude that a
43 change in the behavior of the ENSO/IMR corre-
44 lations has occurred. The series is resampled
45 1000 times in random 21-year chunks, and 5th
46 and 95th percentiles of the 1000 sample correla-
47 tion coefficients are computed. When the series
48 of observed running correlation is compared to
49 the bootstrapped 90% confidence range they find
50 that in recent decades the sliding correlations
51 have exceeded the upper confidence bound (i.e.

52 are closer to zero than would be expected un-
53 der the hypothesis of constant correlation) and
54 conclude that the ENSO/IMR relationship has
55 become weaker. Implicitly, the authors have ex-
56 amined each of the 121 individual values of
57 the running correlations. This creates multiple
58 testing issues: even when all observations are
59 drawn from the same distribution, we expect
60 that 10% will fall outside of a 90% confidence
61 range purely by chance. In light of these issues,
62 the statistical significance of the exceedance
63 of the 95% upper confidence bound in 1980 is
64 unclear.

65 There appears to be no clear consensus on the
66 best way to attach statistical significance to ob-
67 served changes in correlation. A formal statisti-
68 cal test with clearly defined hypotheses could be
69 useful. Parametric methods for detecting change
70 points in a variety of contexts can be found in
71 Chen and Gupta (2000). Their parametric likeli-
72 hood ratio test for detecting change points will be
73 presented with applications to the covariance re-
74 lationship between IMR and ENSO, and for com-
75 parison, that between the Northeast Brazilian
76 Rainfall and ENSO (see Chiang et al. 2000) for
77 a discussion of this relationship.) In contrast to
78 previous approaches, we will use the covariance
79 matrix Σ rather than the correlation coefficient
80 $\rho_{xy} = \sigma_{xy}/\sigma_x\sigma_y$ as the parameter of interest. A
81 change in ρ can reflect changes in the covariance
82 of the two processes, a change in the variance
83 of one or both of the processes, or both. To detect
84 a shift in variance rather than covariance, a
85 univariate version of Chen and Gupta's test will
86 be used.

87 In the applications presented the climate pro-
88 cesses are slightly auto-correlated. However, the
89 results of our analysis are virtually unchanged
90 after removing the autoregressive components
91 of the time series. The methods presented are
92 intended for use on independent sequences of
93 observations, but are also appropriate for the resid-
94 uals of an ARIMA model. Local change point
95 detection, a variation of the change point detec-
96 tion algorithm (Mercurio and Spokoyny 2004;
97 Giacomini et al. 2006) is also presented, with
98 the intent to increase power under multiple
99 change point alternatives, for example in situa-
100 tions where a shift is followed by a reversal to the
101 original state, a situation that is important in the
102 long term study of ENSO and IMR.

2. Methodology

Likelihood ratio tests are a fundamental part of classical statistical hypothesis testing, and the literature on their general properties is extensive. Lehmann (1997) is a good resource for many aspects of hypothesis testing.

Given n independent observations $\mathbf{x}_1 \cdots \mathbf{x}_n$ observed in order, the general null hypothesis for a change point problem is that the probability distribution of the observations remains constant. If F_i is the distribution of \mathbf{x}_i , the null hypothesis is

$$H_0: F_1 = F_2 = \cdots = F_{(n-1)} = F_n \quad (1)$$

and the alternative is

$$H_1: F_1 = \cdots = F_{k_1} \neq F_{(k_1+1)} = \cdots = F_{k_2} \neq F_{(k_2+1)} \\ = \cdots = F_{k_q} \neq F_{(k_q+1)} = \cdots = F_n, \quad (2)$$

where q is the unknown number of change points and $1 < k_1 < \cdots < k_p < n$ are the unknown positions of the change points. If $\mathbf{x}_1 \cdots \mathbf{x}_n$ come from a common parametric family of distributions, then the problem is one of detecting changes in the parameters of $F_1 \cdots F_n$, and the relevant hypotheses become $H_0: \theta_1 = \cdots = \theta_n$ and $H_1: \theta_1 = \cdots = \theta_{k_1} \neq \theta_{(k_1+1)} = \cdots = \theta_{k_2} \neq \theta_{(k_2+1)} = \cdots = \theta_{k_q} \neq \theta_{(k_q+1)} = \cdots = \theta_n$ where θ_i is the vector of parameters for F_i .

The basic test procedure is to formulate the likelihood ratio (LR) based on maximum likelihood estimates of the parameters under the null and alternative hypotheses, as well as the m.l.e. of the change points,

$$\text{LR} = \frac{\text{Likelihood of data under alternative}}{\text{Likelihood of data under null}} \quad (3)$$

and compute a p -value by comparing the observed LR to its distribution under the null hypothesis. In practice $\lambda = \log(\text{LR})$ is used instead of LR. The global procedure outlined by Chen and Gupta (2000) for finding multiple change points is to look for the most significant change point k by testing $\mathbf{x}_1 \cdots \mathbf{x}_n$ using an alternative hypothesis of one change point, and then apply the same test on $\mathbf{x}_1 \cdots \mathbf{x}_k$ and $\mathbf{x}_{k+1} \cdots \mathbf{x}_n$ iteratively until the null hypothesis is no longer rejected. However, under some multiple change point alternatives the global procedure may lack power, and local change point detection maybe more appropriate. Chen and Gupta have derived the asymptotic distribution of λ for

several distributions, including univariate and multivariate normal, gamma, exponential, poisson and binomial, making the method widely applicable.

In the examples to be presented the data are yearly observations of vector-valued climate indices, and the parameter of interest is the covariance matrix. Specifically, we will test for significant changes in the covariance structure of the ENSO-precipitation relationship in India and Brazil in the last 130/150 years. The ENSO/IMR and ENSO/Brazilian rainfall series are modeled as multivariate normal. One can test for changes in the mean vector of their distributions, in the covariance matrix, or for a simultaneous change in both parameters. When the mean is known, it can be removed from the series which can then be modeled as mean zero. In this case, the null and alternative hypotheses are $H_0: \Sigma_1 = \cdots = \Sigma_n$ and $H_1: \Sigma_1 = \cdots = \Sigma_k \neq \Sigma_{k+1} = \cdots = \Sigma_n$ where k is the position of the single change point at each iteration. The observations are $\mathbf{x}_1 \cdots \mathbf{x}_n$, each a vector of length m . In this case $m = 2$. Under H_0 , the joint likelihood function of $\mathbf{x}_1 \cdots \mathbf{x}_n$ is

$$L_0(\Sigma) = \frac{1}{2\pi} \frac{mn/2}{|\Sigma|^n} \exp \left\{ -\frac{1}{2} \sum_{i=1}^n \mathbf{x}_i' \Sigma^{-1} \mathbf{x}_i \right\}, \quad (4)$$

so the log-likelihood is

$$\log(L_0(\Sigma)) = -\frac{mn}{2} \log 2\pi - n \log |\Sigma| \\ - \frac{1}{2} \sum_{i=1}^n \mathbf{x}_i' \Sigma^{-1} \mathbf{x}_i. \quad (5)$$

Σ is unknown so the maximum likelihood estimate $\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i' \mathbf{x}_i$ is used, making the maximum log likelihood function

$$\log L_0(\hat{\Sigma}) = -\frac{mn}{2} \log 2\pi \\ - \frac{n}{2} \log \left| \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i' \mathbf{x}_i \right| - \frac{n}{2}. \quad (6)$$

Under H_1 , $\mathbf{x}_1 \cdots \mathbf{x}_k$ are iid $N_m(0, \Sigma_1)$ and $\mathbf{x}_{k+1} \cdots \mathbf{x}_n$ are iid $N_m(0, \Sigma_2)$. The mle's for Σ_1 and Σ_2 are

$$\hat{\Sigma}_1 = \frac{1}{k} \sum_{i=1}^k \mathbf{x}_i' \mathbf{x}_i \quad \text{and} \quad \hat{\Sigma}_2 = \frac{1}{n-k} \sum_{i=k+1}^n \mathbf{x}_i' \mathbf{x}_i \quad (7)$$

1 respectively, making the maximum log likeli-
 2 hood function under H_1

$$\log L_1(\widehat{\Sigma}_1, \widehat{\Sigma}_2) = -\frac{mn}{2} \log 2\pi - \frac{k}{2} \log \left| \frac{1}{k} \sum_{i=1}^k \mathbf{x}_i' \mathbf{x}_i \right| - \frac{n-k}{2} \log \left| \frac{1}{n-k} \sum_{i=k+1}^n \mathbf{x}_i' \mathbf{x}_i \right| - \frac{n}{2}, \quad (8)$$

4 where $|\Sigma|$ is the determinant of Σ . The position
 5 of the change point k must also be estimated, and
 6 the mle k is the value which maximizes $\log(L_1)$.
 7 The mle's can only be obtained for $m \leq k \leq n - m$,
 8 so the maximum log likelihood ratio is

$$\lambda_n = \max_{m < k < n-m} \left(\log \left| \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i' \mathbf{x}_i \right|^n - \log \left| \frac{1}{k} \sum_{i=1}^k \mathbf{x}_i' \mathbf{x}_i \right|^k - \log \left| \frac{1}{n-k} \sum_{i=k+1}^n \mathbf{x}_i' \mathbf{x}_i \right|^{n-k} \right)^{\frac{1}{2}}. \quad (9)$$

10 Chen and Gupta (2000) have calculated the
 11 limiting distribution of λ_n under H_0 :

$$\lim_{n \rightarrow \infty} P(a_n \lambda_n - b_{mn} \leq x) = e^{-2e^{-x}} \quad \text{for all } x \in \mathbf{R},$$

13 with

$$a_n = (2 \log \log n)^{\frac{1}{2}} \quad \text{and} \\ b_{mn} = 2 \log \log n + \frac{m}{2} \log \log \log(n) - \log \left(\Gamma \left(\frac{m}{2} \right) \right), \quad (10)$$

15 where m is the dimension of the multivariate nor-
 16 mal distribution.

17 This distribution is used to calculate the ap-
 18 proximate p -value of an observed λ .

19 Perhaps a more common case is one in which
 20 the mean is unknown but the same under the null
 21 and alternative hypotheses. In this case, the max-
 22 imum likelihood estimates for $\boldsymbol{\mu}$, Σ_1 and Σ_n can
 23 be found numerically by maximizing the log-
 24 likelihood function under the alternative,

$$-\frac{mn}{2} \log(2\pi) - \frac{k}{2} \log |\Sigma_1| - \frac{n-k}{2} \log |\Sigma_n| - \frac{1}{2} \left[\sum_{i=1}^k (\mathbf{x}_i - \boldsymbol{\mu})' \Sigma_1^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) + \sum_{i=k+1}^n (\mathbf{x}_i - \boldsymbol{\mu})' \Sigma_n^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) \right], \quad (11)$$

for a specific k . Estimates for all possible change
 points must be computed to find the maximum
 of all likelihood ratios. In practice, this can be
 tedious and may present difficulty for large m .
 Simulation studies indicate that this numerical
 optimization may not be necessary, however.
 For n as small as 25 no substantive difference
 in the distribution of the test statistic was found
 between the case where a process was truly
 mean-zero and the one in the sample average
 was removed from a process with non-zero
 mean. Asymptotically, removing the sample
 mean is justified by the law of large numbers,
 which states that as the sample size increases
 $(\mathbf{x}_i - \bar{\mathbf{x}}) \rightarrow (\mathbf{x}_i - \boldsymbol{\mu})$ almost surely. This is the
 approach taken in the examples below. Independ-
 ence between observations is preserved after
 removing the sample mean under the assumption
 of i.i.d. normality, thus it is important to con-
 firm that this assumption is reasonable before
 proceeding.

The logic behind the univariate test for homo-
 geneity of variance in the case of known mean is
 the same. The likelihood ratio test statistic is

$$\lambda_n = \max_{1 < k < n-1} \left(n \log \hat{\sigma}_1^2 - k \log \hat{\sigma}_1^2 - (n-k) \log \hat{\sigma}_n^2 - \frac{n}{2} \right). \quad (12)$$

where

$$\hat{\sigma}^2 = \frac{\sum_{i=1}^n (x_i - \mu)^2}{n}, \quad (13)$$

$$\hat{\sigma}_1^2 = \frac{\sum_{i=1}^k (x_i - \mu)^2}{k}, \quad \text{and}$$

$$\hat{\sigma}_n^2 = \frac{\sum_{i=k+1}^n (x_i - \mu)^2}{n-k}, \quad (14)$$

The asymptotic distribution under H_0 is

$$\lim_{n \rightarrow \infty} P(a_n \lambda_n - b_n \leq x) = e^{-2e^{-x}} \quad \text{for all } x \in \mathbf{R}, \quad (15)$$

with

$$a_n = (2 \log \log(n))^{\frac{1}{2}} \quad \text{and} \\ b_n = \frac{1}{2} \log \log \log(n) + 2 \log \log(n) - \log \left(\Gamma \left(\frac{1}{2} \right) \right). \quad (16)$$

In practice, if there is doubt as to whether the
 large sample distribution of the test statistic is

1 appropriate, critical values can be computed via
2 simulation.

3 The above test procedures all assume that the
4 mean of the process does not change. If one
5 wishes to test the hypothesis

$$H_0: \Sigma_1 = \cdots = \Sigma_n, \boldsymbol{\mu}_1 = \cdots = \boldsymbol{\mu}_n \quad (17)$$

7 against

$$H_1: \Sigma_1 = \cdots = \Sigma_k \neq \Sigma_{k+1} = \cdots = \Sigma_n, \boldsymbol{\mu}_1 = \cdots = \boldsymbol{\mu}_k \neq \boldsymbol{\mu}_{k+1} = \cdots = \boldsymbol{\mu}_n, \quad (18)$$

9 the relevant test statistic as proposed by Chen
10 and Gupta (2000) is

$$\max_{m < k < n-m} (n \log |\widehat{\Sigma}| - k \log |\widehat{\Sigma}_1| - (n-k) \log \widehat{\Sigma}_n)^{\frac{1}{2}}, \quad (19)$$

12 where

$$\widehat{\Sigma} = \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})', \quad (20)$$

$$\begin{aligned} \widehat{\Sigma}_1 &= \frac{1}{k} \sum_{i=1}^k (\mathbf{x}_i - \bar{\mathbf{x}}_k)(\mathbf{x}_i - \bar{\mathbf{x}}_k)', \widehat{\Sigma}_n \\ &= \frac{1}{n-k} \sum_{i=k+1}^n (\mathbf{x}_i - \bar{\mathbf{x}}_{n-k})(\mathbf{x}_i - \bar{\mathbf{x}}_{n-k})', \end{aligned} \quad (21)$$

$$\bar{\mathbf{x}}_k = \frac{1}{k} \sum_{i=1}^k \mathbf{x}_i, \bar{\mathbf{x}}_{n-k} = \frac{1}{n-k} \sum_{i=k+1}^n \mathbf{x}_i \quad (22)$$

16 It is important to note that the individual log-
17 likelihood ratios are unreliable near the ends of
18 the time series and typically produce very high
19 values at near $k = m$ and $k = n - m$. We sug-
20 gest including only the values roughly between
21 $k = m + 3$ and $k = n - m - 3$ in the maximum
22 above.

23 The limiting distribution is

$$\lim_{n \rightarrow \infty} P(a_n \lambda_n - b_{2m} \leq x) = e^{-2e^{-x}} \quad \text{for all } x \in \mathbf{R}, \quad (23)$$

25 with

$$\begin{aligned} a_n &= (2 \log \log n)^{\frac{1}{2}} \quad \text{and} \\ b_{2m} &= 2 \log \log n + m \log \log \log(n) - \log \Gamma(m). \end{aligned} \quad (24)$$

27 The above procedures are valid in the case
28 where observations are independent between time
29 points. In the presence of autocorrelation, the

30 same analysis can be applied to the process after
31 the autoregressive components are removed (pre-
32 whitening). In practice, the components removed
33 will be based on sample estimates of the autore-
34 gressive parameters, and the sensitivity of the test
35 to this extra source of variability may need to be
36 explored.

37 Local change point detection is a stepwise pro-
38 cedure which begins by testing an interval subset
39 of the data for homogeneity and increases the
40 size of the interval until a change point is de-
41 tected or the interval being tested reaches the
42 length of the entire series. At each stage of the
43 testing procedure, the test statistic is the one out-
44 lined above. To begin, a family of intervals
45 $I = \{I_j, j = 0, 1, \dots\}$ is defined. Each interval is
46 of the form $I_j = [n - m_j, n]$, with $m: m_0 <$
47 $m_1 < \dots < n$ where n is the length of the series.
48 Beginning with $I = I_0$, the procedure is to test I
49 for homogeneity against the alternative of one
50 change point as above. If the hypothesis of ho-
51 mogeneity is not rejected, the next larger interval
52 is tested until a change point is detected or the
53 largest possible interval is tested. If, for some
54 interval a change point is detected at some point
55 k , the procedure begins again using intervals of
56 the form $I_j = [k - m_j, k]$. Because multiple tests
57 are being performed, the critical values at each
58 stage are adjusted using the Bonferonni method,
59 which is to replace the significance level α
60 with α/J where J is the number of tests being
61 performed.

62 Following Giacomini et al. (2006), we set
63 $m_j = m_0 c^j$, where $c = 1.5$ and $m_0 = 10$. For a
64 time series of a given length n , this will yield J
65 intervals contained in $[1, n]$, which lead to J
66 different tests of homogeneity. To control the prob-
67 ability of H_0 being rejected falsely (type I error)
68 for at least one interval at α , we set the rejection
69 level for each interval at α/J .

70 The goal of this adjustment procedure is to
71 increase power under some multiple change
72 point alternatives. Imagine a 150-year time series
73 in which there is a change in a parameter θ at
74 years 50 and 100, and that θ has value θ_1 in the
75 intervals $[1, 50]$ and $[101, 150]$ and θ_2 in the
76 interval $[51, 100]$ as shown in Fig. 2. The global
77 approach is to begin by testing the entire series
78 for homogeneity using the test statistic

$$\lambda_n = \max_{m < k < n-m} \lambda_k. \quad (25)$$

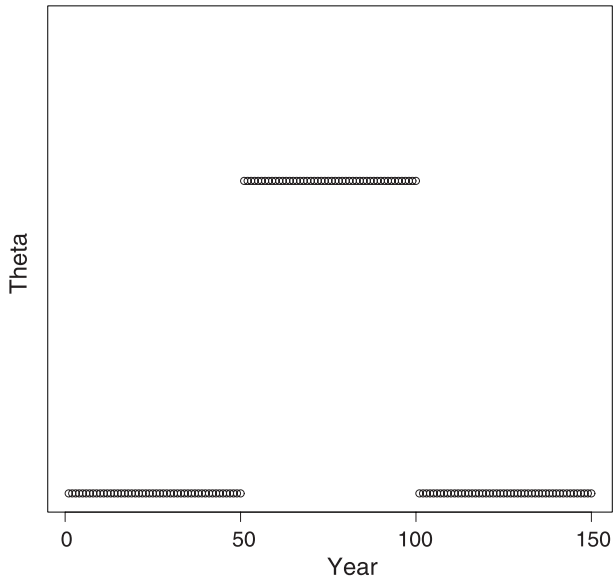


Fig. 2. Local change point detection maybe more powerful than a global test when a shift in any parameter, here designated as theta, is followed by a reversal

1 The maximum should occur at either year 50
 2 or year 100. Supposing it is at year 50, the test
 3 statistic depends on two maximum likelihood
 4 estimates, $\hat{\theta}_1$ computed from the years [1, 50], and
 5 $\hat{\theta}_2$ based on the years [51, 150]. The size of the
 6 test statistic (and thus the probability of rejecting
 7 H_0) increases with the difference between $\hat{\theta}_1$ and
 8 $\hat{\theta}_2$. $\hat{\theta}_1$ should be close to θ_1 , but $\hat{\theta}_2$ will be a
 9 compromise between θ_2 and θ_1 . If the test for
 10 homogeneity were to be performed locally on the
 11 interval [1, 100] or [51, 150], the MLEs would
 12 not be distorted by the intervals [101, 150] or

[1, 50], respectively. A greater difference between $\hat{\theta}_1$ and $\hat{\theta}_2$ should be expected, increasing the probability of rejection.

Disadvantages of the local procedure as compared to the global method include decreased power under single change point alternatives due to the adjusted significance levels, and the somewhat arbitrary nature of the interval selection process, which may influence results. This modified procedure is potentially important in long-term studies of climate variability, where several changes and reversals may be present.

3. Application

Two relationships were examined for a significant change in covariance structure, the ENSO/IMR series and an ENSO/Brazil rainfall series. The latter was studied by Chiang et al. (2000), who found that the generally weak negative correlation peaked in the mid 20th century and, more significantly after 1980 or so. For the ENSO/IMR series, monthly rainfall totals and Pacific SST observations from 1871 to 2003 were both averaged over the months July to September. For the ENSO/Brazil series, monthly rainfall totals and SST were averaged over the months April to June, from 1856 to 2001. Each of the three individual series was tested for normality and homogeneous mean, and each assumption appears reasonable.

The ENSO series were slightly autocorrelated. The best fitting ARMA model, as chosen

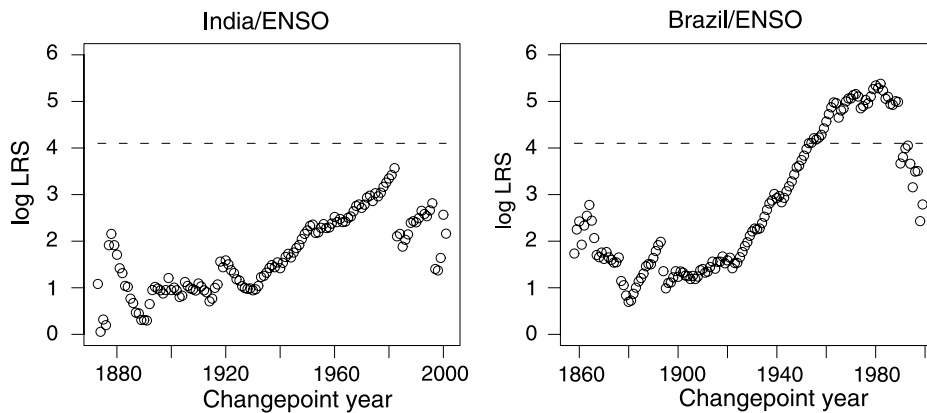


Fig. 3. The likelihood ratio test statistics at each possible change point year. 95% significance is indicated by the dotted line. The test statistic for the Brazil series is at a maximum in 1982, with a p -value of less than 1%. The test statistic for the India series is maximized in 1980, with a p -value of 0.12. Although the significance of the change point for the India series is less clear than in the Brazilian series case, the similarity between the two series is suggestive

1 using the Akaike information criterion (AIC) was
 2 AR(2). The raw data were tested for change-
 3 points, as was a pre-whitened series from which
 4 the AR component had been removed. The re-
 5 sults were virtually identical for both the raw
 6 and pre-whitened data.

7 The global analysis for the ENSO/IMR series
 8 may suggest an event in 1980 with a correspond-
 9 ing p -value of 0.12. Figure 3 shows the graph of
 10 the log-likelihood functions versus change point
 11 year k . Peaks indicate years where a change point
 12 is relatively likely (although not necessarily
 13 statistically significant). The dashed line is the
 14 critical value at the 5% level of significance.
 15 Approximate critical values obtained via simula-
 16 tion rather than the asymptotic distribution of the
 17 test statistic give a p -value of 0.14.

18 The sample covariance matrix in the time pe-
 19 riod from 1871 to 1980 was

$$\widehat{\Sigma}_1 = \begin{pmatrix} 4.4 & -0.659 \\ -0.659 & 0.27 \end{pmatrix}, \quad (26)$$

21 from 1980 to 2003 it was

$$\widehat{\Sigma}_2 = \begin{pmatrix} 3.76 & -0.207 \\ -0.207 & 0.404 \end{pmatrix}. \quad (27)$$

23 The local and global analysis yielded the same
 24 conclusions, although in the next section it will
 25 be shown that in some situations the results can
 26 differ.

27 The univariate version of the test designed to
 28 detect changes in variance was performed on the
 29 ENSO series, finding no significant changes in
 30 variance. For the ENSO/Brazil series, a signifi-
 31 cant change ($p = 0.005$) in the covariance matrix
 32 was detected in 1982. A test for equality of vari-
 33 ance on the Northeast Brazil Rainfall series re-
 34 veals that there is a shift in the variance of the
 35 univariate process which is significant at the 1%
 36 level. Thus, there is a significant change in the
 37 covariance structure in the ENSO/Brazil rela-
 38 tionship, all or part of which can be explained
 39 by an increase in the variance of the Brazilian
 40 rainfall. The observed covariance matrices were

$$\widehat{\Sigma}_1 = \begin{pmatrix} 0.59 & -0.075 \\ -0.075 & 0.27 \end{pmatrix} \quad (28)$$

42 pre-1982, and

$$\widehat{\Sigma}_2 = \begin{pmatrix} 2.43 & -0.27 \\ -0.27 & 0.46 \end{pmatrix} \quad (29)$$

44 from 1982 to 2001. It should be noted that an
 45 increase in the variance of the Brazilian rainfall
 46 process results in decreased predictability using
 47 ENSO, since $\rho_{xy} = \sigma_{xy}/\sigma_x\sigma_y$. This is consistent
 48 with the findings of Chiang et al. (2000), al-
 49 though not with the reasons proposed in that
 50 paper.

51 As can be seen in Fig. 3, the first time the
 52 likelihood ratio crosses the 5% threshold is
 53 around 1960, and it continues to increase until
 54 the peak in 1982. Unlike under a sequential anal-
 55 ysis framework, the estimated change point is not
 56 at the point of first crossing the significance
 57 threshold, but rather the point at which the test
 58 statistic is maximized, i.e. the mle for the change
 59 point.

4. Power 60

61 Simulations were run to assess the power (the
 62 probability of rejection when the null hypotheses
 63 is false) of the global and local methods under
 64 specific alternatives. The power of the global test
 65 under one-change point alternatives is assessed
 66 using series of 150 simulated bivariate normal
 67 observations, the first 75 of which are generated
 68 using one covariance matrix, and the last 75 using
 69 a different covariance matrix. Thousand series of
 70 length 150 are generated and tested for homoge-
 71 neity. The percentage of simulations in which the
 72 null hypothesis is rejected is an estimate of the
 73 power of the test. The results from these simula-
 74 tions are shown in Table 1 for $\alpha = 0.05$.

75 Some findings based on simulations can be
 76 stated in a general manner. In a situation of con-
 77 stant variance and changing covariance, the mag-
 78 nitude of the change in covariance must be rather
 79 large to achieve reasonable power. If both vari-
 80 ance and covariance are changing, power in-
 81 creases with the magnitude of the absolute
 82 difference in the determinants of the covariance
 83 matrices. The power of the test decreases steadily
 84 as the change point approaches the beginning or
 85 end of the time series. The power of the global
 86 test appears to be greater for 1 change point than
 87 for 2 or more.

88 Because the local test comprises multiple in-
 89 dividual hypothesis tests, the interpretation of the
 90 p -values is somewhat more difficult. To compare
 91 the power of the local test, using the intervals
 92 defined in Sect. 2, in comparison to the global

Table 1. The results of simulations to study the power of the chang epoint detection method are above. For each combination of pre and post-change covariance matrices, 1000 simulations of length 150 were created with a change point after 75 observations. The percentage of the 1000 simulations in which the p -value fell below 5% is the observed power of the test

Σ before change	Σ after change	Power	Σ before	Σ after	power
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.2 \\ 0.2 & 1 \end{pmatrix}$	0.08	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.2 \\ 0.2 & 1 \end{pmatrix}$	0.45
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.4 \\ 0.4 & 1 \end{pmatrix}$	0.27	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.4 \\ 0.4 & 1 \end{pmatrix}$	0.16
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	0.81	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	0.07
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.8 \\ 0.8 & 1 \end{pmatrix}$	1	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0.8 \\ 0.8 & 1 \end{pmatrix}$	0.35
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$	1	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$	1
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0 \\ 0 & 1 \end{pmatrix}$	0.16	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0 \\ 0 & 1 \end{pmatrix}$	0.94
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.245 \\ 0.245 & 1 \end{pmatrix}$	0.38	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.245 \\ 0.245 & 1 \end{pmatrix}$	0.72
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.5 \\ 0.5 & 1 \end{pmatrix}$	0.83	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.5 \\ 0.5 & 1 \end{pmatrix}$	0.41
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.74 \\ 0.74 & 1 \end{pmatrix}_1$	1	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 0.74 \\ 0.74 & 1 \end{pmatrix}$	0.16
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 1 \\ 1 & 1 \end{pmatrix}$	0.83	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 1 \\ 1 & 1 \end{pmatrix}$	0.37
$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 1.5 \\ 1.5 & 1 \end{pmatrix}$	1	$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix}$	$\begin{pmatrix} 1.5 & 1.5 \\ 1.5 & 1 \end{pmatrix}$	1

1 test in a multiple change point situation, 100 se-
 2 ries were generated using

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad (30)$$

4 as the covariance matrix for observations 1 ...
 5 50, and 101 ... 150, and

$$\begin{pmatrix} 1 & 0.6 \\ 0.6 & 1 \end{pmatrix} \quad (31)$$

7 for observations 51 ... 100. The observed power
 8 in detecting at least one change at a significance
 9 level of 5% for the local and global tests were
 10 68% and 55%, respectively, suggesting that the
 11 local test is more powerful, 26% more powerful
 12 in this case, under some alternatives.

13 **5. Summary and discussion**

14 We have presented a parametric test for retro-
 15 spective detection of change points in covariance
 16 matrices which we have not previously seen in

17 analysis of climate data. The test assumes the ob-
 18 servations are multivariate normal and inde-
 19 pendent in time. A hypothesis of homogeneous
 20 covariance is compared to one of at least one
 21 change point using a likelihood ratio. If a change
 22 point is detected, the data is split at the estimated
 23 change point and the two segments are tested for
 24 additional change points. The procedure is re-
 25 peated until no more change points are found.
 26 In situations where a shift is followed by a re-
 27 versal, a more powerful test maybe created by
 28 segmenting the data and testing segments of in-
 29 creasing size.

30 Two series were tested for changes in co-
 31 variance: ENSO/Indian Monsoon Rainfall and
 32 ENSO/Northeast Brazil Rainfall. In the former,
 33 the resulting p -value was 0.12. This finding does
 34 not lend strong support to the claim that the
 35 ENSO/Monsoon relationship has recently chan-
 36 ged. If one exists, the most likely year for a
 37 change point is 1980. For the ENSO/Northeast
 38 Brazil series, a significant change (p -value <0.01)

1 was detected in 1982. All or part of the latter
 2 change can be attributed to a change in the vari-
 3 ance of the Brazil series. This finding differs
 4 from the conclusion reached by Chiang et al.
 5 (2000), who argued that a change in the frequen-
 6 cy of strong El Niño is an explanation for a
 7 change in the correlation between the two pro-
 8 cesses. Additional research is necessary to sort
 9 out this inconsistency.

10 The proposed method is designed to detect
 11 abrupt shifts in the probability distributions of
 12 the observed processes, but obviously in some
 13 situations inhomogeneities would be better mod-
 14 eled by continuous trends. Sveinsson and Salas
 15 (2003) explore probability models for climate
 16 processes in the presence of shifts, trends and
 17 oscillatory behavior. Regression methods can be
 18 used to detect and model trends in the mean of a
 19 process, and the evolution of variance can be
 20 modeled using ARCH (autoregressive condition-
 21 al heteroskedastic) or GARCH (generalized autor-
 22 egressive conditional heteroskedasticity, see
 23 Bellerslev 1986) methodology. When trends are
 24 not constant over the entire observed record, a
 25 change point framework may still be needed to
 26 detect the beginnings, ends or reversals of trends.
 27 Likelihood ratios could be constructed in the
 28 above manner, with regression or ARCH param-
 29 eters as the quantities of interest.

30 The interconnection between changes in the
 31 mean and variance of the distribution makes in-
 32 ference more difficult when both types of inho-
 33 mogeneity exist. Changes in mean can disguise
 34 changes in variance and vice versa. The proce-
 35 dure outlined above is constrained to detect only
 36 simultaneous shifts in mean and variance, and
 37 may not perform well in other situations. A
 38 Bayesian approach in which uncertainty in both
 39 location and variance are addressed separately
 40 would be useful in creating a more flexible, real-
 41 istic model.

42 The test used in this analysis is designed for a
 43 fixed sample size and, does not assume *a priori*
 44 that any period in the observed record is without
 45 changes. Alternatively, when a stable reference
 46 period is available and the aim is to detect
 47 changes as new data is accumulated, methods
 48 from statistical quality control, such as sequential
 49 probability ratio test (SPRT) or cumulative sum

(CUSUM), procedures, can be employed. A re-
 view of recent developments in using control
 charts for monitoring covariance matrices can
 be found in Yeh et al. (2006). If the assumption
 of known starting values for the parameters of
 interest is added to the analysis, a more powerful
 test maybe available.

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